1. General description

The TDA8931 is a switching power stage for high efficiency class-D audio power amplifier systems.

It contains a Single-Ended (SE) power stage, drive logic, protection control logic, a full differential input comparator and a HVP charger to charge the SE capacitor. With this amplifier a compact 1×20 W closed loop self-oscillating digital amplifier system can be built. The TDA8931 has a high efficiency so that a heat sink is not required up to 20 W (RMS). The system operates on an asymmetrical and a symmetrical supply voltage.

2. Features

- High efficiency
- Operating voltage asymmetrical from 12 V to 35 V
- Operating voltage symmetrical from ± 6 V to ± 17.5 V
- Thermally protected
- No heat sink required
- Charger for single-ended capacitor
- No pop sound

3. Applications

- Flat panel television sets
- Flat panel monitors
- Multimedia systems
- Wireless speakers
- Micro systems

4. Quick reference data

5. Ordering information

6. Block diagram

7. Pinning information

7.1 Pinning

7.2 Pin description

Table 3: Pin description

8. Functional description

8.1 General

The TDA8931 is a switching power stage for high efficiency class-D audio power amplifier systems. It contains a Single-Ended (SE) power stage, drive logic, protection control logic, a full differential input comparator and a HVP charger to charge the SE capacitor (see [Figure](#page-2-0) 1). With this amplifier a compact 1×20 W closed loop self-oscillating digital amplifier system can be built. A second order low-pass filter converts the PWM output signal into an analog audio signal across the speaker.

8.2 Interfacing

The operating modes of the TDA8931 can be controlled by pins POWERUP and ENABLE. Both pins refer to pin CGND. The device has three modes:

- **•** Sleep mode
- **•** Standby mode
- **•** Operating mode

When pin POWERUP $=$ LOW, the power comparator is in Sleep mode, independent of the signal on pin ENABLE. In Sleep mode the SE capacitor charger will be discharged.

When pin POWERUP = HIGH and pin $ENABLE = LOW$ the device is in Standby mode. In Standby mode the device is DC biased and the SE capacitor will be charged and the output is floating.

When both pins POWERUP and ENABLE are HIGH, the device is in Operating mode. A level at pin POWERUP greater than 11 V can also enter the Operating mode, independent of the level on pin ENABLE (see [Table](#page-4-0) 4).

Remark: The switch-on sequence is important. First pin POWERUP = HIGH, then pin $FNARI F = HIGH$

Table 4: Interfacing

8.3 Input comparator

The input comparator has a full differential input and is optimized for low noise and low offset. This results in maximum flexibility in the application.

8.4 Half supply voltage input reference (pin HVPI)

When the device is in Standby mode, the external capacitor C6 (see [Figure](#page-14-0) 5) will be charged until it reaches the half of the supply voltage. This pin charges capacitor C6 within 0.5 seconds.

Pin HVPI will be on its final level of $0.5V_P$ before the device starts switching. This results into a plop-noise free start-up behavior.

8.5 Half supply voltage capacitor charger (pin HVP)

When the device is in Standby mode, the SE capacitor C15 (see [Figure](#page-14-0) 5) will be charged until it reaches the half of the supply voltage. This current charges capacitor C15 within 0.5 seconds when a capacitor of 1000 uF is used. When the voltage on pin HVP has reached the level of $0.5V_P$ it releases pin ENABLE for external use.

When the device is in Operating mode, pin HVP is switched to floating to minimize dissipation.

When the supply voltage drops, capacitor C15 is discharged and the device is switched off to avoid plop noise.

8.6 Protections

Overtemperature, overcurrent, overvoltage and undervoltage sensors are included in the TDA8931. When one of these sensors exceeds its threshold level the output power stage is switched off and the output stage becomes floating. After 1.5 µs the device will try to restart. When the fault condition is removed the output stage is switched on.

Table 5: Overview protections

[1] Pin DIAG = LOW for minimal 1.5 μ s.

8.6.1 Overtemperature protection (OTP)

If the junction temperature T_i exceeds the threshold level of approximately 150 °C then the device will shut down immediately. The device will start switching again when the temperature drops.

8.6.2 Overcurrent protection (OCP)

If the output current exceeds the maximum output current threshold level (e.g. when the loudspeaker terminals are short-circuited it will be detected by the current protection) the device will shut-down.

8.6.3 Overvoltage protection (OVP)

When the supply voltage applied to the TDA8931 exceeds the maximum supply voltage threshold level the device will shut down. The supply voltage on which the device stops operating is determined by two external resistors R1 and R2.

The overvoltage protection level can be determined by the formula:

$$
V_{P(OVP)} = \frac{R1 + R2}{R2} \times V_{OVP} \tag{1}
$$

Where:

 $V_{P(OVP)} =$ overvoltage protection level of supply voltage

 $R1$ = external resistor

R2 = external resistor

 V_{OVP} = 1.27 V reference voltage.

Example: The TDA8931 has to shut down at 24 V. When we choose $R2 = 10 \text{ k}\Omega$, then R1 has to be 178 kΩ and $V_{P(O\vee P)}$ becomes 24 V.

Remark: When pin OVP is connected to V_{SSD} the V_{P(OVP)fix} level is used.

8.6.4 Undervoltage protection (UVP)

When the supply voltage applied to the TDA8931 drops below the minimum supply voltage threshold level the device is internally set to Standby mode.

8.6.5 Supply voltage drop protection

When the TDA8931T is switched off with the supply, it will be switched off before it reaches the voltage on pin HVP. This prevents switch-off pop noise. This function is not self recovering. The TDA8931T can be recovered by switching to Sleep mode or by removing the supply voltage.

8.6.6 Overdissipation protection (ODP)

In case of a short-circuit across the speaker the dissipation is minimized by the ODP. When the OCP and the OTP are on the same time activated, an over dissipation is defined. The device is set to Sleep mode and is not self-recovering. When pin POWERUP $= 0$ V or the supply voltage is removed, the device is recovered.

9. Internal circuitry

Power comparator 1 × **20 W**

Power comparator 1 × **20 W**

10. Limiting values

11. Thermal characteristics

[1] Measured in the application board.

- [2] V_p = 22 V; R_L = 4 Ω; V_{ripple} = 2 V (p-p); f_{ripple} = 100 Hz with feed-forward network (470 kΩ and 15 nF).
- [3] Strongly depending on where you measure on the case.

12. Static characteristics

Table 9: Characteristics

 $V_P = 22$ V; $T_{amb} = 25$ °C; $f_{carrier} = 290$ kHz; unless otherwise specified.

Table 9: Characteristics …continued

[1] V_{IH} on pin ENABLE must not exceed V_{DDA} .

[2] The overvoltage protection can be controlled external (see [Section](#page-5-1) 8.6.3).

13. Dynamic characteristics

Table 10: Characteristics

 V_P = 22 V; T_{amb} = 25 °C; R_L = 4 Ω ; unless otherwise specified.

[1] Measured in the application board.

 $Rev.01 -$ 14 January 2004

Preliminary data sheet Rev. 01 — 14 January 2004 14 January 2004 15 of 31 © Koninklijke Philips Electronics N.V. 2005. All rights re **15 of 31**

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Power comparator 1 × **20 W**

14.1 Output power estimation

The output power, just before clipping, can be estimated using the following equation:

$$
P_{o(1\%)} = \frac{\left(\frac{R_L}{R_L + R_{DSon} + R_{coil} + R_{ESR}} \times V_P\right)^2}{8 \times R_L}
$$
 (2)

Where:

 $P_{0(1%)}$ = output power just before clipping at THD = 1 %

 R_1 = load impedance

 R_{DSon} = on-resistance power switch

 R_{coil} = series resistance output coil

 $R_{FSR} = ESR of the single-ended capacitor$

 V_P = supply voltage (V_{DDP} – V_{SSP})

Example: Substituting R_L = 4 Ω, R_{DSon} = 0.22 Ω (at T_j = 25 °C), R_{coil} = 0.045 Ω, $R_{ESR} = 0.06 \Omega$ and $V_P = 22 V$ results in output power $P_0 = 12.9 W$.

The output power at THD = 10 % can be estimated by:

$$
P_{o(10\%)} = 1.25 \times P_{o(1\%)} \tag{3}
$$

[Figure](#page-16-0) 6 shows the estimated output power as a function of the supply voltage for different load impedances.

14.2 Output current limiting

The output current is limited by the OCP with a threshold level of 3.3 A (minimum). During normal operation the output current should not exceed this threshold level, otherwise the output signal is distorted. The peak output current should stay below 3.3 A and can be estimated using the following equation:

$$
I_O \le \frac{V_P}{2 \times (R_{DSon} + R_L + R_{coil} + R_{ESR})} \le 3.3\tag{4}
$$

Where:

 I_{Ω} = output current in the load in

 V_P = supply voltage (V_{DDP} – V_{SSP})

 R_{DSon} = on-resistance power switch

 R_L = load impedance

 R_{coil} = series resistance output coil

 $R_{FSR} = ESR of the single-ended capacitor$

Example: With a 4 Ω load the OCP will be triggered below a supply voltage of 28 V. This will result in an absolute maximum output power of $P_0 = 26$ W at THD = 10 %.

14.3 Low pass filter considerations

For a flat frequency response (second order Butterworth filter) it is necessary to change the LC-filter components (L1 and C14) according to the speaker impedance. [Table](#page-17-0) 12 shows the required components values in case of a 4 W, 6 W or 8 W speaker impedance.

14.4 Thermal behavior (printed-circuit board considerations)

The SO20 package of the TDA8931T has special thermal corner leads, significantly increasing the power capability (reducing R_{th}). The corner leads (pins 1, 10, 11 and 20) should be attached to a copper area (V_{SS}) on the PCB for cooling.

The typical thermal resistance $R_{th(j-a)}$ of the TDA8931T is 24 K/W (free air and natural convection) when soldered on a double sided FR4 PCB with 35 µm copper layer and cooling area of approximately of 28 cm2.

14.4.1 Thermal layout including vias

The bottom side of the double-sided PCB is used to place the SMD components including the TDA8931T and the majority of the signal tracks. The topside is used to place the leaded components.

The remaining area on both top and bottom layer are filled with ground plane for a proper cooling. In this way it is possible to have a cooling area available of about:

- **•** 40 % of the PCB area on the bottom (60 % for signal tracks and SMD components)
- **•** 90 % of the PCB area on the top (10 % for signal tracks)

The PCB area required for a typical mono amplifier is 21.5 cm^2 resulting in a cooling area of about 28 cm2. Thermal vias should be placed close to corner leads for a proper heat flow to the top layer of the PCB. [Figure](#page-18-0) 7 is showing the thermal vias indicated as black dots and [Figure](#page-18-1) 8 is showing the heat flow to the copper area on the top layer.

14.4.2 Thermal considerations

To estimate the maximum junction temperature, the following equation can be used:

$$
T_{j(max)} = T_{amb} + R_{th(j-a)} \times P_d \tag{5}
$$

Where:

 T_{amb} = ambient temperature

 P_d = power dissipation in the TDA8931T

 $R_{th(i-a)}$ = thermal resistance from junction to ambient (24 K/W)

To estimate the power dissipation, the following equation can be used:

$$
P_d = P_o \times \left(\frac{l}{\eta} - l\right) \tag{6}
$$

Where:

 P_d = power dissipation

 P_0 = RMS output power (W)

 $η =$ efficiency of total application (0.91 for R_L = 8 Ω and 0.89 for R_L = 4 Ω)

The derating curves of the dissipated power as a function of ambient temperature for several values of $R_{th(i-a)}$ are illustrated in [Figure](#page-19-0) 9. A maximum junction temperature $T_i = 150$ °C is taken into account.

Example: TDA8931T mono amplifier, with substituting $P_0 = 1 \times 20$ W, $R_{th(i-a)} = 24$ K/W, $P_d = 2.47$ W results in a junction temperature $T_{j(max)} = 119$ °C.

For this example the estimated maximum junction temperature at a high ambient temperature of 60 °C for a mono amplifier driving 4 Ω speaker impedance stays below the OTP threshold level of 150 °C.

14.5 Measured performance figures of mono amplifier with TDA8931

Table 13: Characteristics

[1] Operates down to UVP threshold level and operates up to OVP threshold level.

14.6 Curves measured in typical application

Power comparator 1 × **20 W**

Power comparator 1 × **20 W**

15. Test information

Remark: Only valid if the TDA8931 is used as an audio amplifier.

15.1 Quality information

The General Quality Specification for Integrated Circuits, SNW-FQ-611 is applicable.

Power comparator 1 × **20 W**

16. Package outline

Fig 18. Package outline SOT163-1 (SO20)

17. Soldering

17.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our Data Handbook IC26; Integrated Circuit Packages (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

17.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement. Driven by legislation and environmental forces the worldwide use of lead-free solder pastes is increasing.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 seconds and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 °C to 270 °C depending on solder paste material. The top-surface temperature of the packages should preferably be kept:

- **•** below 225 °C (SnPb process) or below 245 °C (Pb-free process)
	- **–** for all BGA, HTSSON..T and SSOP..T packages
	- **–** for packages with a thickness ≥ 2.5 mm
	- **–** for packages with a thickness < 2.5 mm and a volume ≥ 350 mm3 so called thick/large packages.
- **•** below 240 °C (SnPb process) or below 260 °C (Pb-free process) for packages with a thickness < 2.5 mm and a volume < 350 mm³ so called small/thin packages.

Moisture sensitivity precautions, as indicated on packing, must be respected at all times.

17.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- **•** Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- **•** For packages with leads on two sides and a pitch (e):
	- **–** larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;

– smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

• For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time of the leads in the wave ranges from 3 seconds to 4 seconds at 250 °C or 265 °C, depending on solder material applied, SnPb or Pb-free respectively.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

17.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 seconds to 5 seconds between 270 °C and 320 °C.

17.5 Package related soldering information

Table 14: Suitability of surface mount IC packages for wave and reflow soldering methods

[1] For more detailed information on the BGA packages refer to the (LF)BGA Application Note (AN01026); order a copy from your Philips Semiconductors sales office.

- [2] All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods.
- [3] These transparent plastic packages are extremely sensitive to reflow soldering conditions and must on no account be processed through more than one soldering cycle or subjected to infrared reflow soldering with peak temperature exceeding 217 °C ± 10 °C measured in the atmosphere of the reflow oven. The package body peak temperature must be kept as low as possible.
- [4] These packages are not suitable for wave soldering. On versions with the heatsink on the bottom side, the solder cannot penetrate between the printed-circuit board and the heatsink. On versions with the heatsink on the top side, the solder might be deposited on the heatsink surface.
- [5] If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- [6] Wave soldering is suitable for LQFP, QFP and TQFP packages with a pitch (e) larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- [7] Wave soldering is suitable for SSOP, TSSOP, VSO and VSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.
- [8] Image sensor packages in principle should not be soldered. They are mounted in sockets or delivered pre-mounted on flex foil. However, the image sensor package can be mounted by the client on a flex foil by using a hot bar soldering process. The appropriate soldering profile can be provided on request.
- [9] Hot bar soldering or manual soldering is suitable for PMFP packages.

18. Revision history

19. Data sheet status

[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

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Power comparator 1 × **20 W**

23. Contents

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